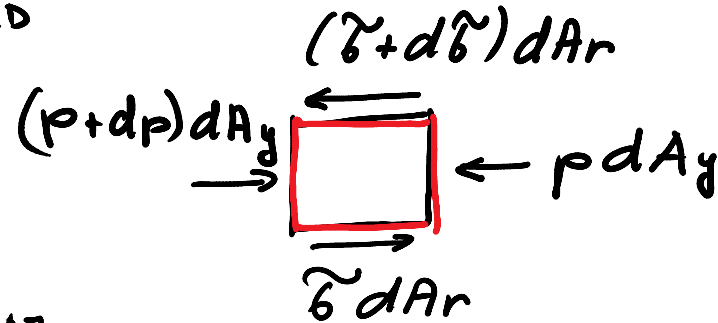
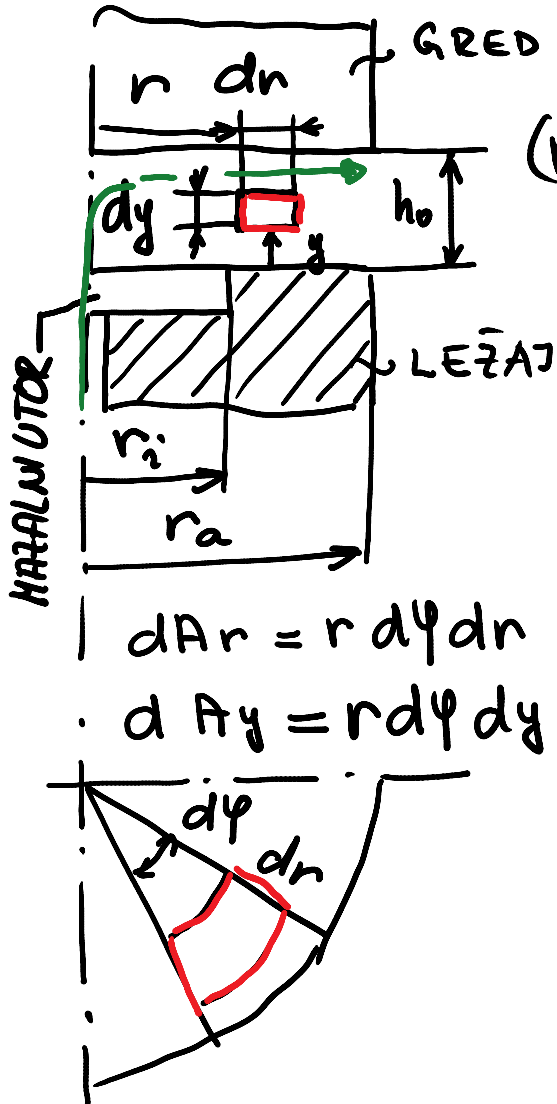


AZSIALNI DRŠNI LEŽAJ

NI ŽA IŽPIT IŽ
SEI!



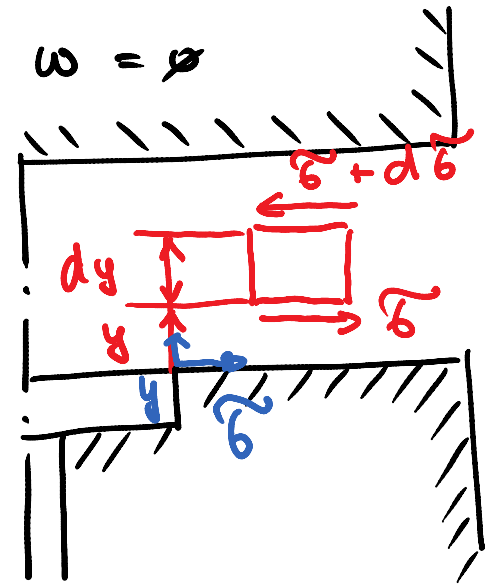
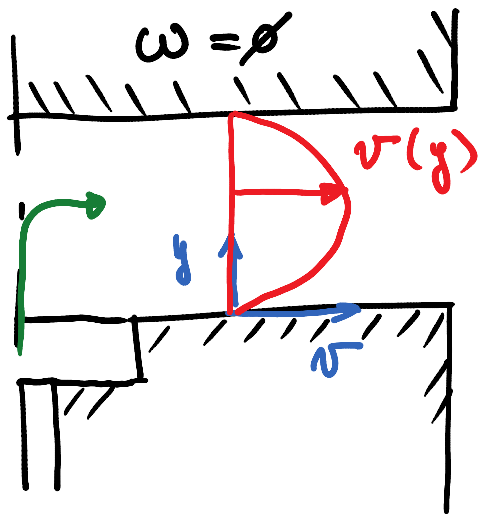
RAVNOTEŽJE SIL

$$0 = (p+dp)dA_y - p dA_y + \tilde{\tau} dA_r - (\tilde{\tau}+d\tilde{\tau})dA_r$$

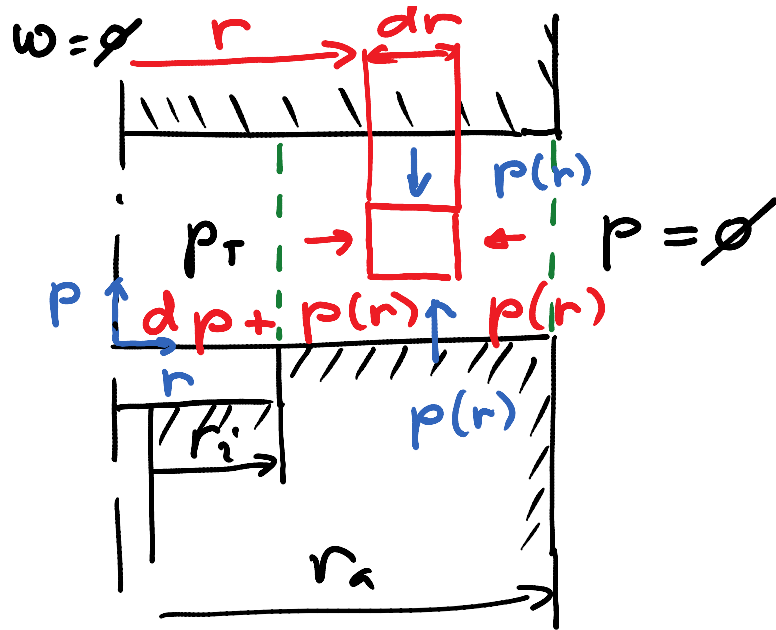
$$dp dA_y = d\tilde{\tau} dA_r$$

$$dp r d\varphi dy = d\tilde{\tau} r d\varphi dn$$

$$\frac{dp}{dr} = \frac{d\tilde{\tau}}{dy}$$



$\rightarrow v(y)$



$$\tau = \eta \frac{dv}{dy} = \tau(y)$$

$$\forall \epsilon \exists \delta = \eta \frac{d\sigma}{dy} \quad \exists \epsilon \frac{dp}{dn} = \eta \frac{d^2\sigma}{dy^2} \quad \blacksquare$$

R.P. $y = \phi$; $\sigma = \phi$ NEDOLOŽENO INTEGRIRAMO

$$y = h_0; \sigma = \phi$$

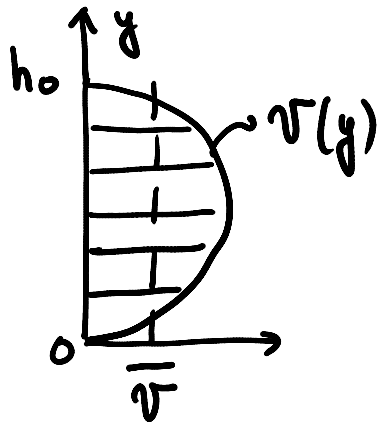
$$\frac{d\sigma}{dy} = \frac{1}{\eta} \frac{dp}{dn} y + C_1$$

$$\sigma(y) = \frac{1}{2\eta} \frac{dp}{dn} y (y - h_0) \quad \blacksquare$$

$$\sigma(y) = \frac{1}{2\eta} \frac{dp}{dn} y^2 + C_1 y + C_2$$

$$C_2 = \phi$$

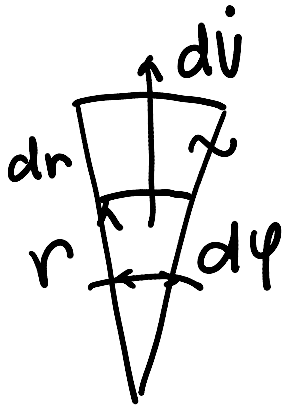
$$\phi = \frac{1}{2\eta} \frac{dp}{dn} h_0^2 + C_1 h_0 \Rightarrow C_1 = -\frac{1}{2\eta} \frac{dp}{dn} h_0$$



POUPREČNA HITROST

$$\begin{aligned} \bar{v} &= \frac{1}{h_0} \int_0^{h_0} v(y) dy = \frac{1}{2\eta h_0} \frac{dp}{dr} \left[\int_0^{h_0} y^2 dy - h_0 \int_0^{h_0} y dy \right] \\ &= \frac{1}{2\eta h_0} \frac{dp}{dr} \left[\frac{h_0^3}{3} - \frac{h_0^3}{2} \right] = -\frac{h_0^2}{12\eta} \frac{dp}{dr} \end{aligned}$$

$$d\dot{V} = \bar{v} dA_y$$



VOLUMSKI PRETOK

$$\int_0^{\dot{V}} d\dot{V} = -\frac{h_0^2}{12\eta} \frac{dp}{dr} r \int_0^{2\pi} d\varphi \int_0^{h_0} dy$$

$$\dot{V} = -\frac{h_0^2}{12\eta} \frac{dp}{dr} r 2\pi h_0 = -\frac{h_0^3 r \pi}{6\eta} \frac{dp}{dr}$$

ČER JE \dot{V} ZNAN IN GA DOLOČA ČRPALKA LAHKO IZRAČUNAMO
TLA $p(r)$

$$\int dp = - \frac{\dot{V} \rho \eta}{h_0^3 \pi} \int \frac{dr}{r}$$

R.P. $r = r_a ; p(r) = \phi$

$$p(r) = - \frac{\dot{V} \rho \eta}{h_0^3 \pi} \ln r + C_1$$

$$p(r_a) = \phi = - \frac{\dot{V} \rho \eta}{h_0^3 \pi} \ln r_a + C_1$$

$$C_1 = \frac{\dot{V} \rho \eta}{h_0^3 \pi} \ln r_a$$

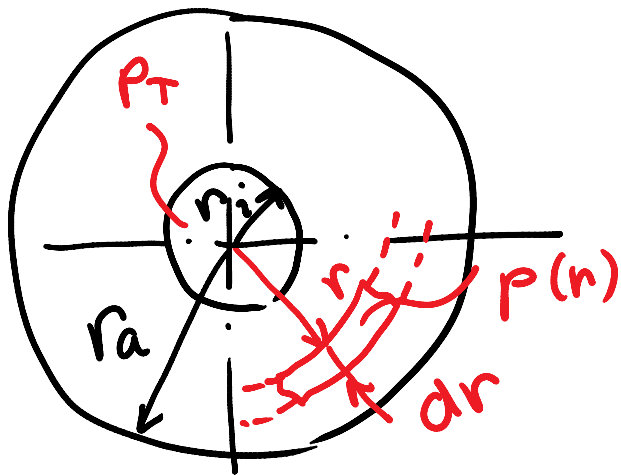
$$p(r) = \frac{\rho \cdot \eta \dot{V}}{h_0^3 \pi} \ln \frac{r_a}{r} \quad \blacksquare$$

OB PREDPOSTAVI, DA POTRANMO TLAŽ V HAZALNEM UTORU P_T
 LAHKO IZRAČUNAMO POTREBNI VOLUHŠI PRETOČ \dot{V}

$$p(r_i) = p_T = \frac{6\eta \dot{V}}{h_0^3 \pi} \ln \frac{r_a}{r_i}$$

$$\dot{V} = \frac{p_T h_0^3 \pi}{6\eta \ln \frac{r_a}{r_i}} \quad \blacksquare$$

SILA, ŠI JO LAHKO PREVŽAME LEŽAJ



$$\int_0^F dF = 2\pi p_T \int_{r_i}^{r_a} r dr$$

$$+ 2\pi \int_{r_i}^{r_a} p(r) r dr$$

$$\begin{aligned}
 F &= 2\pi \int_0^{r_i} p_T r dr + 2\pi \int_{r_i}^{r_a} p(r) r dr = \frac{\bar{p}}{2} \frac{p_T (r_a^2 - r_i^2)}{\ln \frac{r_a}{r_i}} \\
 &= \frac{2\bar{p} p_T r_i^2}{2} + \frac{2\bar{p} p_T}{\ln \frac{r_a}{r_i}} \left[\int_{r_i}^{r_a} \ln r_a r dr - \int_{r_i}^{r_i} r \ln r dr \right] \\
 &\qquad\qquad\qquad \underbrace{\hspace{10em}}_{I_1} \qquad\qquad\qquad \underbrace{\hspace{10em}}_{I_2}
 \end{aligned}$$

$$I_1 = \ln r_a \frac{r_a^2 - r_i^2}{2}$$

$$\begin{aligned}
 u &= \ln r & du &= \frac{1}{r} \\
 v' &= r & v &= \frac{r^2}{2}
 \end{aligned}$$

$$I_2 = v \cdot u - \int v u' dr = \frac{r^2}{2} \ln r - \int \frac{r}{2} dr$$

$$= \frac{r^2}{2} \ln r - \frac{r^2}{4} \Big|_{r_i}^{r_a} = \frac{r_a^2}{2} \ln r_a - \frac{r_i^2}{2} \ln r_i - \frac{r_a^2 - r_i^2}{4}$$

V ENAČBO ZA $p(r)$ NAJPREJ VSTAVIMO KONČNO ENAČBO ZA \dot{v}

$$p(r) = \frac{6\eta\dot{v}}{h_0^3\bar{h}} \ln \frac{r_a}{r}$$

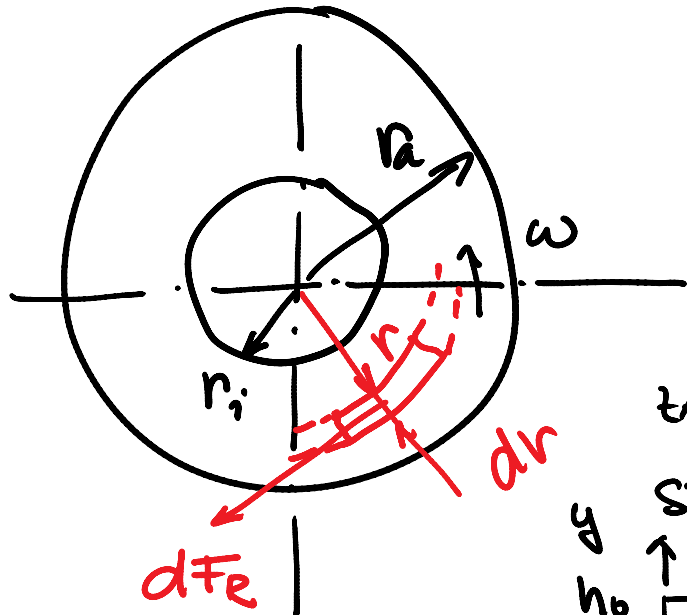
$$\dot{v} = \frac{p_T h_0^3 \bar{h}}{6\eta \ln \frac{r_a}{r_i}}$$

$$p(r) = \frac{\cancel{6\eta}}{\cancel{h_0^3\bar{h}}} \frac{p_T \cancel{h_0^3\bar{h}}}{\cancel{6\eta} \ln \frac{r_a}{r_i}} \ln \frac{r_a}{r} = \frac{p_T}{\ln \frac{r_a}{r_i}} \ln \frac{r_a}{r}$$

PO INTEGRACIJI PO DELIH DOBIMO

$$F = \frac{p_T \bar{h}}{2} \frac{r_a^2 - r_i^2}{\ln \frac{r_a}{r_i}} \quad \blacksquare$$

MOMENT TRENJA

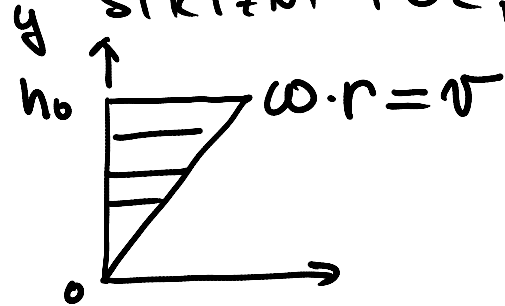


SILA
TRENJA

$$\tau = \frac{dF_e}{2\bar{u}rdr} = \eta \frac{dv}{dy}$$

$$dF_e = 2\bar{u}rdr \eta \frac{dv}{dy}$$

ȚARADI URTEENJA GREDI SE USTUARJIA
STRIȚNI TOȚ, ȚATO JE $\frac{dv}{dy} = \text{const}$



$$\frac{dv}{dy} = \frac{\omega r}{h_0} = a \quad \begin{matrix} y = h_0 \\ r = \omega r \\ y = 0 \\ r = 0 \end{matrix}$$

$$v = \omega \cdot r$$

$$v(y) = ay + b$$

$$\omega r = ah_0$$

$$dF_e = 2\bar{u}r^2dr \eta \frac{\omega}{h_0}$$

$$dM_R = dF_R r$$

$$\int_0^{M_R} dM_R = \int r dF_R = \frac{2\bar{n} \eta \omega}{h_0} \int_{r_i}^{r_a} r^3 dr = \frac{\bar{n} \eta \omega}{2 h_0} (r_a^4 - r_i^4) = M_R \blacksquare$$

ΜΟΜ ΤΡΕΝΤΑ

$$P_R = M_R \omega = \frac{\bar{n} \eta \omega^2 (r_a^4 - r_i^4)}{2 h_0} \blacksquare$$

ΜΟΜ ΣΡΑΛΞΕ

$$P_p = \dot{V} P_z \frac{1}{\eta_p} - \text{ΙΣΟΡΙΣΤΕΣ ΣΡΑΛΞΕ}$$

ΤΙΑΣ ΣΡΑΛΞΕ

$$P_z \cong P_T$$

$$P = F \cdot v$$

$$= p A \cdot v = p \dot{V}$$

$$= \left[\frac{N}{m^2} \frac{m^3}{s} \right]$$

BILANCA TOPLI IN PRIRASTEŽ TEMPERATURE

$$P_p + P_e = \frac{dQ}{dt} = \rho c \Delta T \dot{V}$$

TOPLOTA $Q = m \cdot c \Delta T = \rho V c \Delta T$

$$\Delta T = \frac{P_p + P_e}{\rho c \dot{V}} \quad \blacksquare$$